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Inventor                 Paul J. Carreiro

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2  
3 CRUISE MISSILE DEPLOYED SONAR BUOY

4  
5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used  
7 by or for the Government of the United States of America for  
8 governmental purposes without the payment of any royalties  
9 thereon or therefor.

10  
11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The present invention relates to acoustic wave systems and  
14 devices, and more particularly to sonobuoys with component  
15 activating or deployment means.

16 (2) Brief Description of the Prior Art

17 Expanding mission requirements caused by the increased  
18 frequency of regional conflicts and state-sponsored terrorism,  
19 have forced fast attack submarines into littoral operations.  
20 Submarines are well suited for this type of mission, allowing on-  
21 station, forward deployment, without the vulnerability, or force  
22 telegraphing of a surface ship and the associated political and  
23 tactical ramifications. Whether alone, or acting in conjunction

1 with a battle group, the submarine will increasingly be called on  
2 to patrol and prosecute hostile contacts in this challenging  
3 environment as well as deliver precision missile strikes on  
4 inland targets.

5 Hostile submarines are a serious threat to friendly  
6 submarines, as well as to friendly surface ships. One such  
7 danger comprises diesel-electric type submarines, commonly known  
8 as diesel boats. While relatively cumbersome for extended, deep-  
9 water operations, diesel boats are well suited for coastal  
10 defense in the littoral regions. Relatively small, inexpensive  
11 and quiet (when operating on battery power), diesel boats can lie  
12 in wait for an approaching battle group, or patrol quietly just  
13 off the shore in search of submarines and surface craft.

14 While fast attack submarines possess many operational  
15 advantages, there are still considerable risks associated with  
16 entering shallow or "brown" water to search for enemy submarines.  
17 A nuclear-powered fast attack submarine would prove a priceless  
18 propaganda trophy for any hostile country. Many of the same  
19 risks would attend operations by surface ships in such waters.

20 Another submarine hunting method is using an Anti-Submarine  
21 Warfare (ASW) helicopter launched from a surface ship at standoff  
22 distance. This method, however, also entails considerable risk  
23 due to the amount of time the helicopter must spend hovering,

1 while dipping sonar to locate the hostile submarine, leaving it  
2 seriously vulnerable to fire from shore or from small craft.

3 The prior art also discloses the use of buoys or other  
4 discrete deployable devices for housing a sonar apparatus or  
5 other sensors that may be used to monitor an area for hostile  
6 submarine threats. U.S. Patent No. 4,186,374 to Ouellette, for  
7 example, discloses a transducer housing for an air dropped sonar  
8 transducer including a smooth cylindrical case for stowage on  
9 board an aircraft. The case is formed with a separation device,  
10 which permits ejection of the transducer from the case upon  
11 impact with the surface of the ocean, the device being formed of  
12 tabs on the case and chamfers on a cover plate of the case. The  
13 impact of the water on the cover plate is directed by the  
14 chamfers against the tabs to spread them apart thereby releasing  
15 the cover plate and the transducer. Pins on the cover plate  
16 project through apertures in the tabs and press against the side  
17 of the apertures with a preset force to essentially lock the tabs  
18 to the plate until the preset force is overcome by the water  
19 impact.

20 U.S. Patent No. 5,691,957 to Spiesberger discloses an  
21 acoustic tomography telemetry system and method that allows  
22 spatially averaged ocean temperatures to be measured in real-  
23 time. This system includes autonomous acoustic sources mounted

1 on subsurface mooring and receivers that are either suspended  
2 from drifting surface buoys or cabled to shore. The telemetry  
3 method largely eliminates, in real-time, corruption of acoustic  
4 travel times due to wander of the source's mooring by shifting  
5 the start times of tomographic transmissions. Corrections to  
6 source wander are obtained without expending battery energy over  
7 and above that used in conventional tomography experiments.  
8 Standard techniques are used to correct clock errors at the  
9 source in real-time.

10 U.S. Patent No. 5,973,994 to Woodall discloses a sonobuoy  
11 device for tracking and targeting submarines. The sonobuoy  
12 device consists of a sonobuoy having aft and forward sections  
13 interconnected with each other, fin means mounted on the aft  
14 section for flight stabilization of the device during travel  
15 above water from the platform, separation means responsive to  
16 impact of the device with the water upon completion of the travel  
17 thereof for separating the sections of the device from each  
18 other, payload means within the forward section of the device for  
19 listening for an acoustical signal in response to submergence  
20 thereof within the water following the separation of the sections  
21 of the device, flotation means mounted within the device and  
22 inflated in response to the impact with the water for anchoring  
23 the payload means and tethering means connecting the flotation

1 means to the payload means for limiting the submergence thereof  
2 while anchored by the flotation means to a predetermined depth at  
3 which the payload means receives an acoustical signal. An  
4 apparatus comprised of a device with a launching system and a  
5 method for deploying the device also is disclosed.

6 A further improved means for efficiently and cost  
7 effectively deploying sonar buoys with a low degree of risk to  
8 friendly forces is still needed.

#### 10 SUMMARY OF THE INVENTION

11 It is an object of the present invention to provide a device  
12 and method for efficiently and cost effectively monitoring  
13 littoral and other waters for enemy submarines and other threats  
14 with a low degree of risk to friendly forces.

15 It is a further object of the present invention to provide a  
16 means for a submarine-launched cruise missile to lay a wide-area  
17 field of sonar buoys from a standoff distance.

18 This and other objects are accomplished by the apparatus of  
19 the present invention, which is a sonar buoy adapted to be  
20 deployed by a cruise missile. This sonar buoy includes a  
21 flotation device for keeping a portion of the buoy afloat, a  
22 hydrophone, a transmitter for communicating contact and position  
23 information and a releasable means for attaching the sonar buoy

1 to the cruise missile. By means of this device, a means of  
2 monitoring littoral and other waters for enemy submarines and  
3 other threats is provided with a low degree of risk to friendly  
4 forces.

5 Preferably, this sonar buoy may be deployed by a submarine-  
6 launched Tomahawk UGM 109D cruise missile outfitted with sonar  
7 buoys. Originally designed to deliver small sub-munitions to  
8 multiple targets, the UGM 109D features four payload modules,  
9 each holding six packs of sub-munitions. The Tomahawk sonar buoy  
10 device replaces each pack with a payload shell containing a sonar  
11 buoy.

12 This apparatus allows a submarine to lay a wide area field  
13 of sonar buoys from a standoff distance, allowing anti-submarine  
14 warfare (ASW) forces to pinpoint and track hostile contacts from  
15 a safe range before attacking.

16  
17 BRIEF DESCRIPTION OF THE DRAWINGS

18 Other objects, features and advantages of the present  
19 invention will become apparent upon reference to the following  
20 description of the preferred embodiments and to the drawing,  
21 wherein corresponding reference characters indicate corresponding  
22 parts in the drawing and wherein:

FIG. 1 is a vertical cross sectional view of a sonar buoy representing a preferred embodiment of the device of the present invention;

FIG. 2 is a plan schematic illustration showing a preferred method of deploying a plurality of sonar buoys as shown in FIG. 1 over an operating area;

FIG. 3a is a side elevational view of a cruise missile, which may be used to deploy the sonar buoy shown in FIG. 1;

FIG. 3b is a perspective view of a payload module for deploying the sonar buoy shown in FIG. 1;

FIG. 4 is a front elevational view of the sonar buoy shown in FIG. 1 after deployment and activation of its flotation device;

FIG. 5 is a cross sectional view through 5-5 in FIG. 4; and

FIG. 6 is a view similar to FIG. 4 after the hydrophone has been deployed.

#### DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring to FIG. 1, a complete sonar buoy prior to deployment is shown. The sonar buoy shell 10 has the same external dimensions as the sub-munitions pack it replaces. The shell provides impact and underwater protection to the internal components and acts as a platform for the inflatable float 12 and the hydrophone 14. The float well 16 contains the inflatable



1 float 12, antenna 18, lanyard/antenna lead 20, lanyard bundle 22,  
2 CO<sub>2</sub> canister 24, and pyro-activated inflation valve 26. The  
3 upper section of the lanyard/antenna lead 20 is bonded to the  
4 inflatable float 12 and the base of the antenna 18 is bonded to  
5 the top end of the lanyard/antenna lead 20. A tear-through cover  
6 28 seals the float well 16. A hydrophone well 30 contains the  
7 hydrophone 14, weight 32, hydrophone wire spool 34 and hydrophone  
8 wire 36. A perforated hydrophone well cover 38 holds the  
9 hydrophone 14 in place prior to deployment. Two pyro-activated  
10 latches 40 and 42 secure the cover to the sonar buoy shell 10. A  
11 global positioning system (GPS) 44 receives satellite information  
12 from a transceiver 46, calculates the buoy's position and sends  
13 the position information back to the transceiver 46. The  
14 transceiver 46 transmits and receives via the antenna 18 and  
15 lanyard/antenna lead 20. A control unit 48 provides internal  
16 buoy control. A battery 50 provides power for the buoy.  
17 Saltwater sensors 52 detect submergence in saltwater; however,  
18 other sensors such as accelerometers can be used to detect  
19 impact. A scuttle device 54 contains an explosive charge. On  
20 command from the control unit 48, the scuttle device 54 explodes,  
21 severing the sonar buoy shell 10 from the lanyard/antenna lead 20  
22 and the hydrophone wire 36 and destroying the buoy.

1        When a search is ordered, a cruise missile is programed with  
2        waypoints for a circuitous flight path over the desired area.  
3        The submarine launches the cruise missile outfitted with the  
4        sonar buoys. FIG. 2 shows an example mission profile. The  
5        cruise missile ejects the sonar buoys at timed intervals between  
6        waypoints.

7        Referring to FIG. 2, a cruise missile 56 is launched on a  
8        flight path 58. Flight path 58 can be structured using  
9        navigational waypoints 60. Waypoints 60 can be programmed in the  
10       missile 56 and indicated by inertial coordinates, global  
11       positioning system coordinates, or the like. Sonar buoys are  
12       sequentially deployed at predetermined locations 62 along flight  
13       path 58. Locations 62 can be an array or in some other  
14       configuration dictated by the tactical circumstances. The actual  
15       deployment location 62 can be sent by using the GPS receiver  
16       embodied in each buoy. Upon completing buoy deployment, missile  
17       56 enters a final flight path 64 and prepares for self-  
18       destruction. During the final leg 64, the missile flies clear of  
19       the buoy field and friendly contacts and climbs high into the air  
20       then dives sharply into the ocean and sinks. Other tactical  
21       circumstances may require other self-destruction procedures.

22        When the sonar buoy shell 10 hits the ocean, it sinks.  
23        Saltwater touching one or both of the saltwater sensors as at

1 sensor 52 activates the control unit 48. The control unit 48  
2 fires the inflation valve 26, filling the inflatable float 12  
3 with gas from the CO<sub>2</sub> canister. As the inflatable float 12  
4 fills, the tear through cover 28 yields and the float drifts free  
5 of the float well 16, trailing the lanyard/antenna lead 20 behind  
6 it. The inflatable float 12 rises, while the sonar buoy shell 10  
7 sinks, paying out lanyard/antenna lead 20 from the lanyard bundle  
8 22.

9 Referring to FIG. 3a, a Tomahawk cruise missile UGM-109D 66  
10 is shown on which there are two payload modules 68 and 70 on each  
11 of its lateral sides for a total of four payload modules. As is  
12 conventional, the cruise missile 66 also includes a pair of wings  
13 72, a pair of aft horizontal stabilizers 74, a pair of vertical  
14 stabilizers 76 and 78 and air intake 80 and a jet engine. Other  
15 equivalent types of cruise missiles such as those propelled with  
16 rocket motors can be employed with the apparatus and method of  
17 this invention. As is conventional, the cruise missile has a  
18 guidance system (not shown) capable of directing the missile on a  
19 substantially non-ballistic, circuitous flight path.

20 FIG. 3b details payload module 68 just after sonar buoy  
21 ejection. Payload module 68 has six chambers 84 and 86. Each  
22 chamber houses a single sonar buoy as at sonar buoy 88. Each of  
23 these sonar buoys is ejected by activation of conventional

1 explosive bolts in the same way as the Tomahawk cruise missile  
2 UGM-109D 66 operates to deploy sub-munitions. As the sonar buoy  
3 is being ejected closure door 90 pivots on hinge 92 by being  
4 pulled by closure lanyard 94, which is attached to the sonar buoy  
5 88. A closure latch 96 is provided for securing door 90. After  
6 door 90 is secured, closure lanyard 94 breaks free from payload  
7 module 68 at its upper end 97, and breaks free from sonar buoy 88  
8 at weak point 98 and falls into the ocean. Once closed and  
9 latched, the closure door 90 fairs the missile airframe for the  
10 rest of the flight. The other doors, as at closure door 100,  
11 operate in the same manner as closure door 90. Payload module 68  
12 also has an ejector control line 102, which serially activates  
13 the ejection of each of the sonar buoys as at sonar buoy 90. As  
14 is conventional, payload module 68 also has mounting lugs as at  
15 mounting lugs 104 and 106. There is a tear-through cover 108 on  
16 the sonar buoy, which is used in the way described hereafter.  
17 Module operation during and after ejection is similar to the  
18 prior art Tomahawk cruise missile UGM-109D 66 with the exception  
19 of ejecting one pack at a time instead of six.

20 Referring to FIGS. 1 and 4-6, once fully inflated by the CO<sub>2</sub>  
21 canister 24 through valve 26, the inflatable float 12 rides on  
22 the ocean's surface 140 with the sonar buoy shell 10 suspended by  
23 the lanyard/antenna lead 20 below and the hydrophone well 30

1 facing down. The hydrophone well 30 floods and equalizes through  
2 holes in the hydrophone well cover 38. The antenna 18 formerly  
3 stowed flat on top of the inflatable float 12 is attached to the  
4 lanyard/antenna lead 20 such that it now stands straight up at  
5 the top of the inflatable float 12 as shown in FIGS. 4-6.  
6 Referring particularly to FIG. 6, the hydrophone 14 is then  
7 deployed downwardly on hydrophone wire 36. After a brief delay  
8 to allow float deployment and buoy stabilization, the control  
9 unit 48 activates the transceiver 46 and the Global Positioning  
10 System (GPS) 44. The control unit 48 then awaits a coded  
11 transmitter activation signal from a processing unit on a  
12 submarine, surface ship or aircraft. Once activated, the  
13 transceiver's 46 transmitter sends three distinct pieces of  
14 information to shipboard processing unit: the buoy's position as  
15 calculated by the GPS 44, the hydrophone 14 output, and a code  
16 distinct to the individual buoy. Using the information provided  
17 by the sonar buoys, the processor operator could track and  
18 classify hostile contacts in or near the field. Using coded  
19 signals, the processor operator could turn each transmitter on  
20 and off conserving battery power and controlling the size and  
21 shape of the field as the buoys drift. When the power of battery  
22 50 falls below a specified level, or upon request of a coded  
23 destruct signal from a shipboard processor unit, the control unit

1 48 fires the scuttle device 54 destroying the buoy and sinking  
2 the hydrophone 14.

3 For the purposes of this disclosure, a "cruise missile"  
4 means a pilotless aircraft that can be launched from a submarine,  
5 surface ship, ground vehicle or another aircraft, with a range,  
6 which will ordinarily be at least one thousand miles, and which  
7 flies at a relatively constant altitude that can ordinarily be as  
8 low as sixty meters and which has a guidance system capable of  
9 directing it through a substantially non-ballistic flight path.

10 It will be appreciated that because the sonar buoy of the  
11 present invention can be deployed at a standoff distance,  
12 friendly forces can track hostile contacts with little risk of  
13 attack by hostile forces.

14 It will also be appreciated that a method is provided for  
15 manipulating the cruise missile's waypoints, the attack party  
16 could select the size and shape of the initial buoy field.

17 It will also be appreciated that by turning individual buoys  
18 on and off, the processor operator could control the size and  
19 shape of the buoy field to compensate for drift.

20 It will also be appreciated that because the device and  
21 method of the present inventions allows advanced tracking of  
22 contacts, the attacking craft's time in hostile waters is  
23 minimized.

1        It will also be appreciated that the device and method of  
2        the present invention as significant potential to aid in  
3        intelligence gathering for the classification of unknown  
4        contacts.

5        It will also be appreciated that the device and method of  
6        the present invention allows a single submarine to lay multiple  
7        fields, miles apart simultaneously.

8        It will also be appreciated that the device and method of  
9        the present invention facilitates copying and processing of buoy  
10        transmissions by other ASW forces for strike coordination and  
11        asset allocation.

12        In an alternate embodiment, a cruise missile outfitted with  
13        a repeater could loiter near buoy field, thus extending the sonar  
14        buoy's transmission range.

15        In another alternate embodiment, after delivering of the  
16        sonar buoys, a cruise missile outfitted with a radar seeker and  
17        Identification Friend or Foe (IFF) unit and using residual fuel  
18        as an incendiary could seek out and attack a hostile target of  
19        opportunity.

20        In another alternate embodiment, after delivering the sonar  
21        buoys, the cruise missile outfitted with a GPS and using residual  
22        fuel as incendiary, could attack a specific land target.

1        In still another alternate embodiment, the sonar buoys could  
2        be outfitted with a trigger device, and using the existing  
3        scuttle device could be used as anti-personnel weapons to inflict  
4        casualties upon curious and unwary enemy personnel who might  
5        attempt to retrieve them.

6        While the present invention has been described in connection  
7        with the preferred embodiments of the various figures, it is to  
8        be understood that other similar embodiments may be used or  
9        modifications and additions may be made to the described  
10       embodiment for performing the same function of the present  
11       invention without deviating therefrom. Therefore, the present  
12       invention should not be limited to any single embodiment, but  
13       rather construed in breadth and scope.

14



2  
3 CRUISE MISSILE DEPLOYED SONAR BUOY

4  
5 \* ABSTRACT OF THE DISCLOSURE

6 A sonar buoy adapted to be deployed by a cruise missile.

7 This sonar buoy includes a flotation device for keeping a portion  
8 of the buoy afloat, a hydrophone, a transmitter for communicating  
9 contact and position information and releasable means for  
10 attaching the sonar buoy to the cruise missile. By means of this  
11 device, a means of monitoring littoral and other waters for enemy  
12 submarines and other threats is provided with a low degree of  
13 risk to friendly forces. A system for deploying this sonar buoy  
14 in a sonar buoy field is also disclosed.

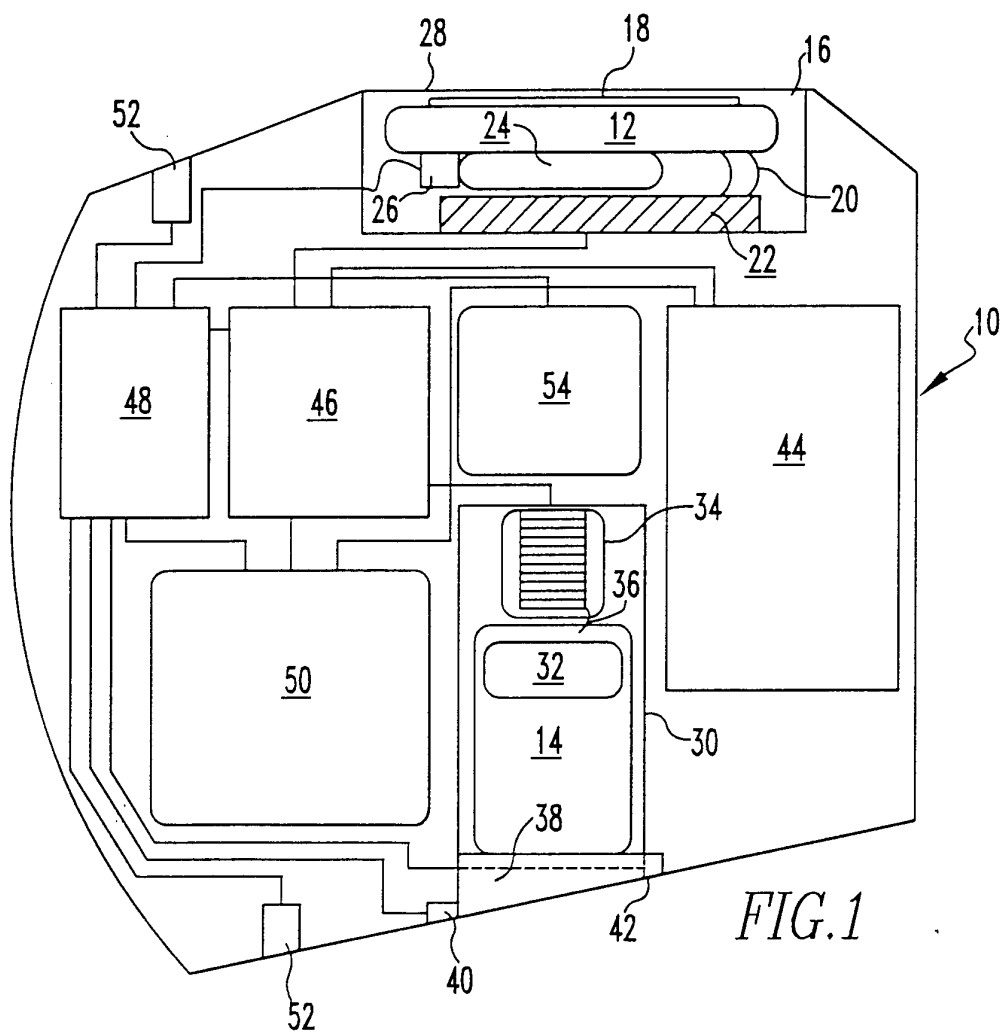


FIG.1

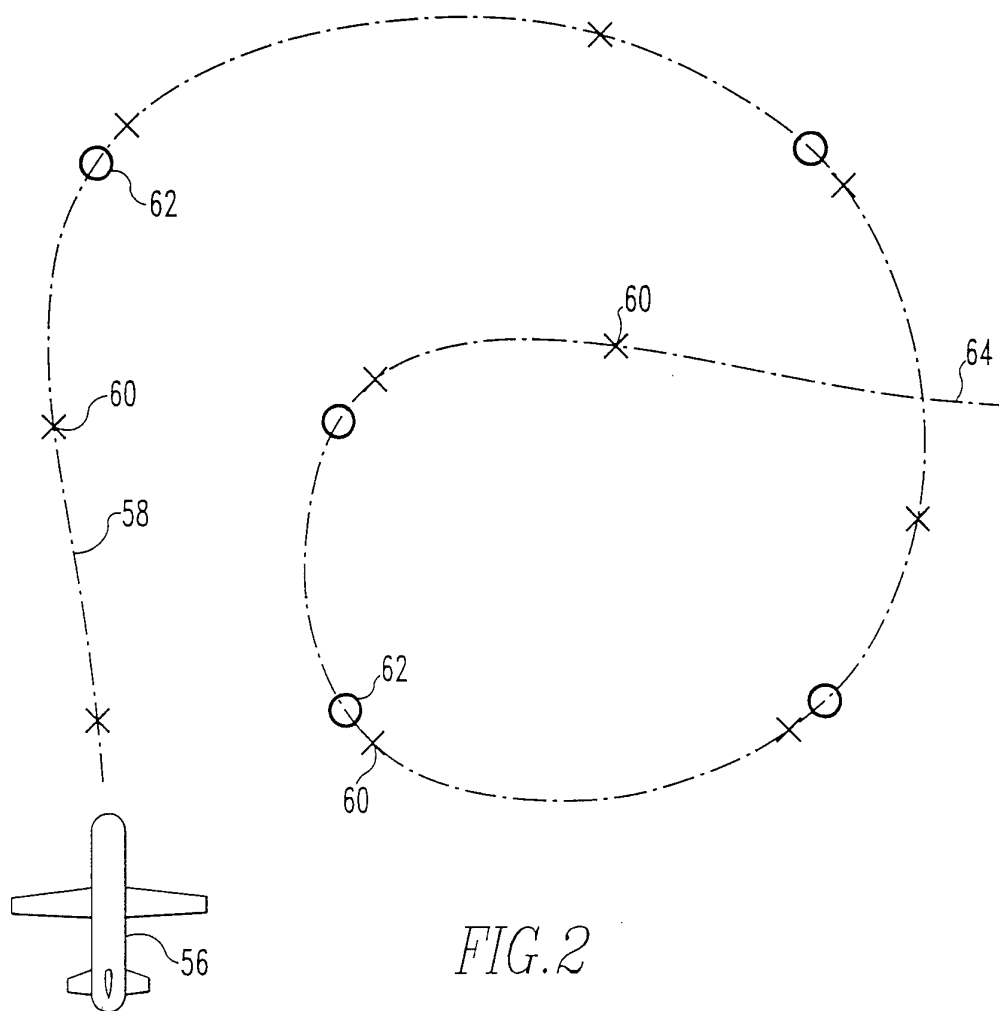


FIG. 2

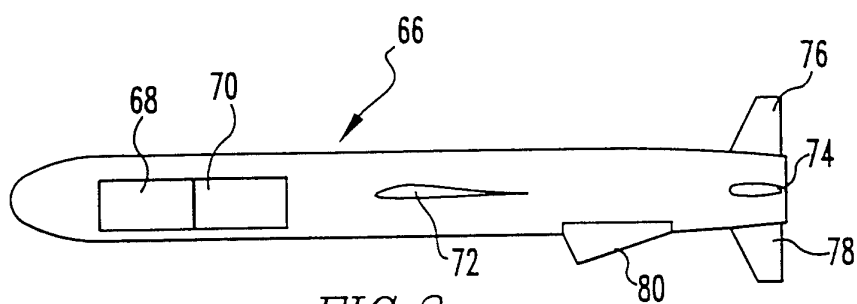


FIG. 3a

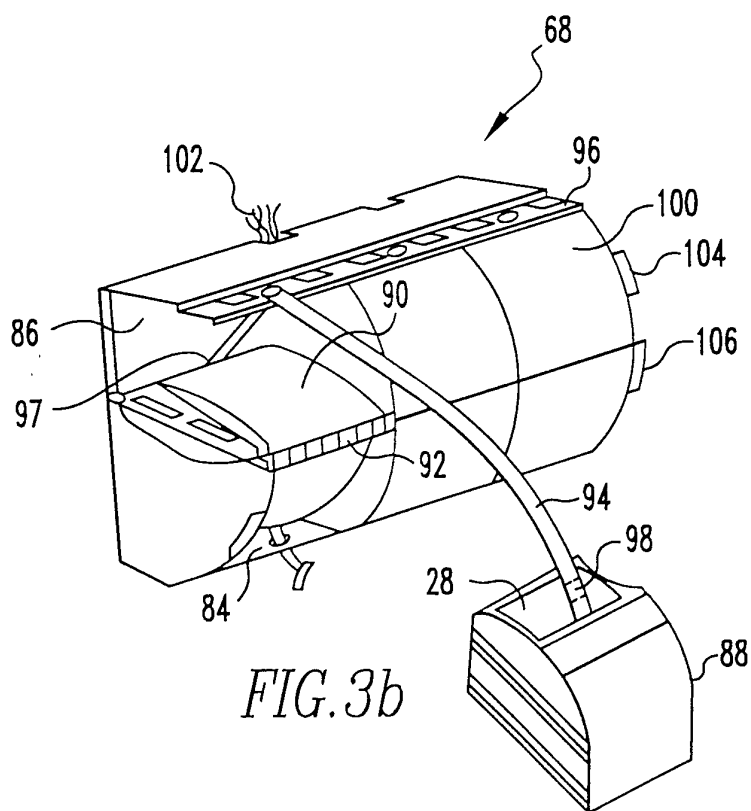


FIG. 3b

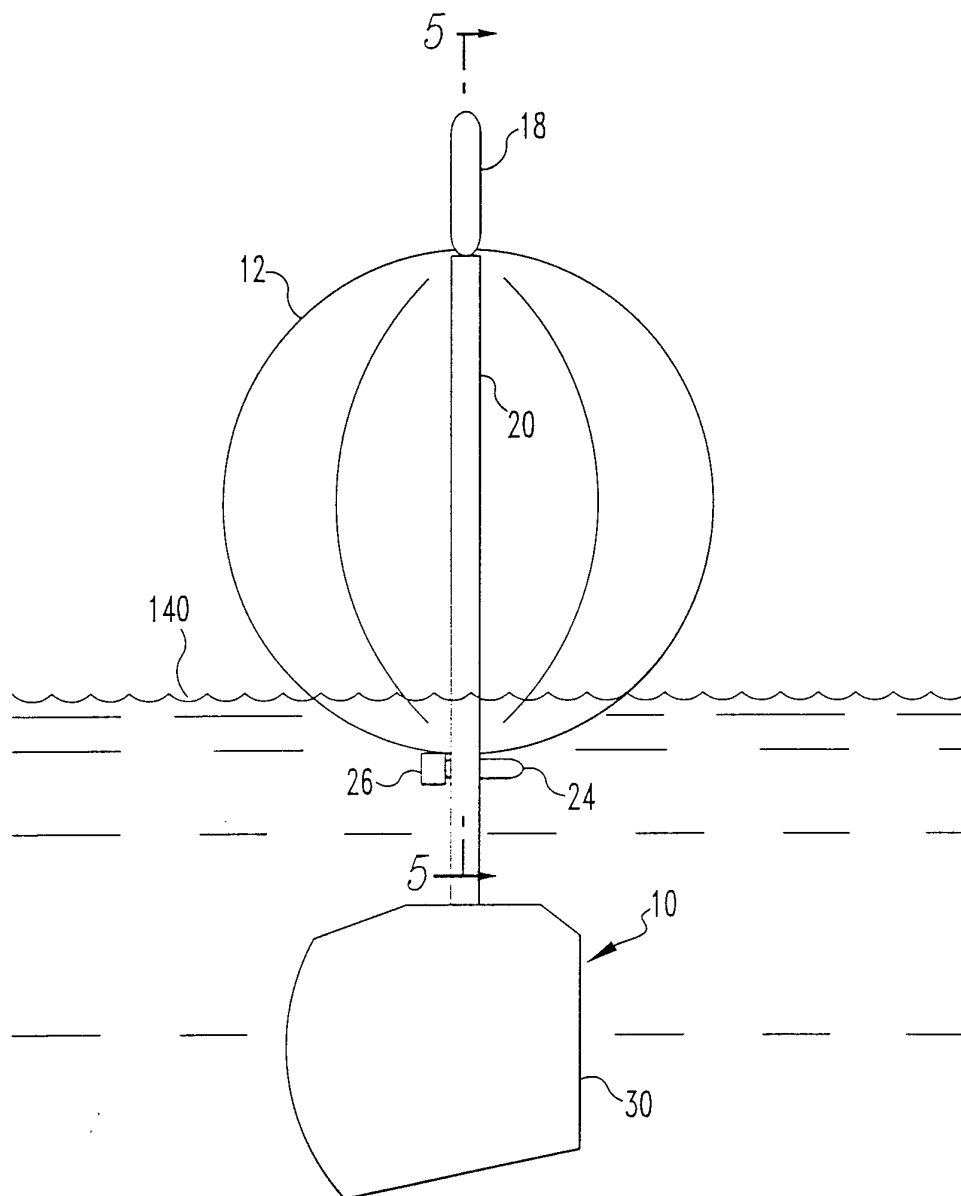


FIG. 4

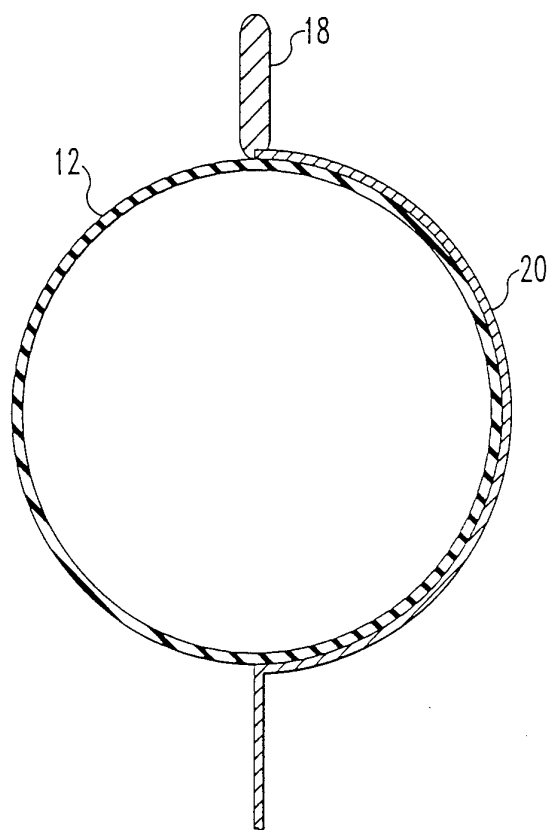


FIG. 5

